



CTL for Testing

Basics

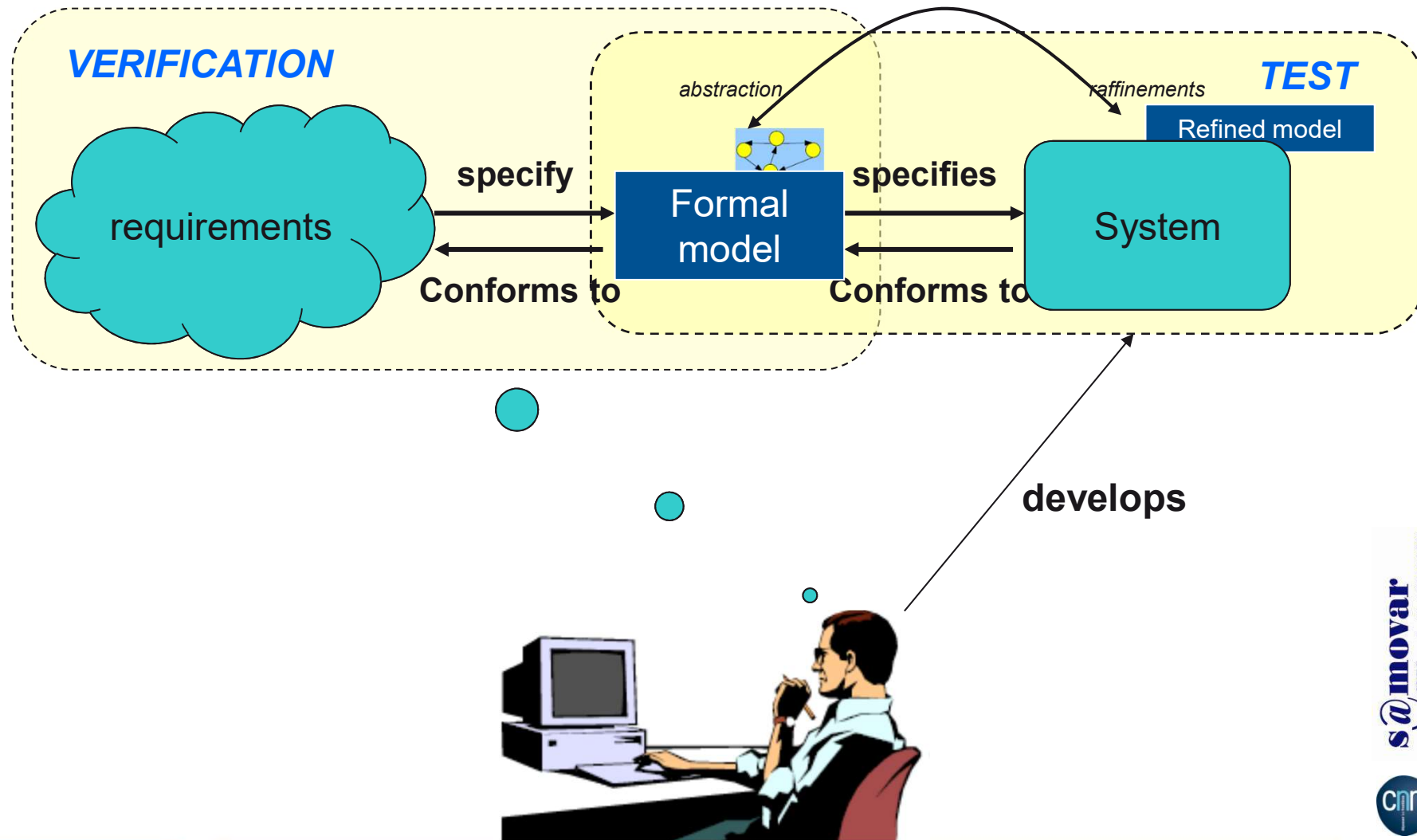
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Flash back – reminder ...



Formal verification techniques

■ 3 main techniques

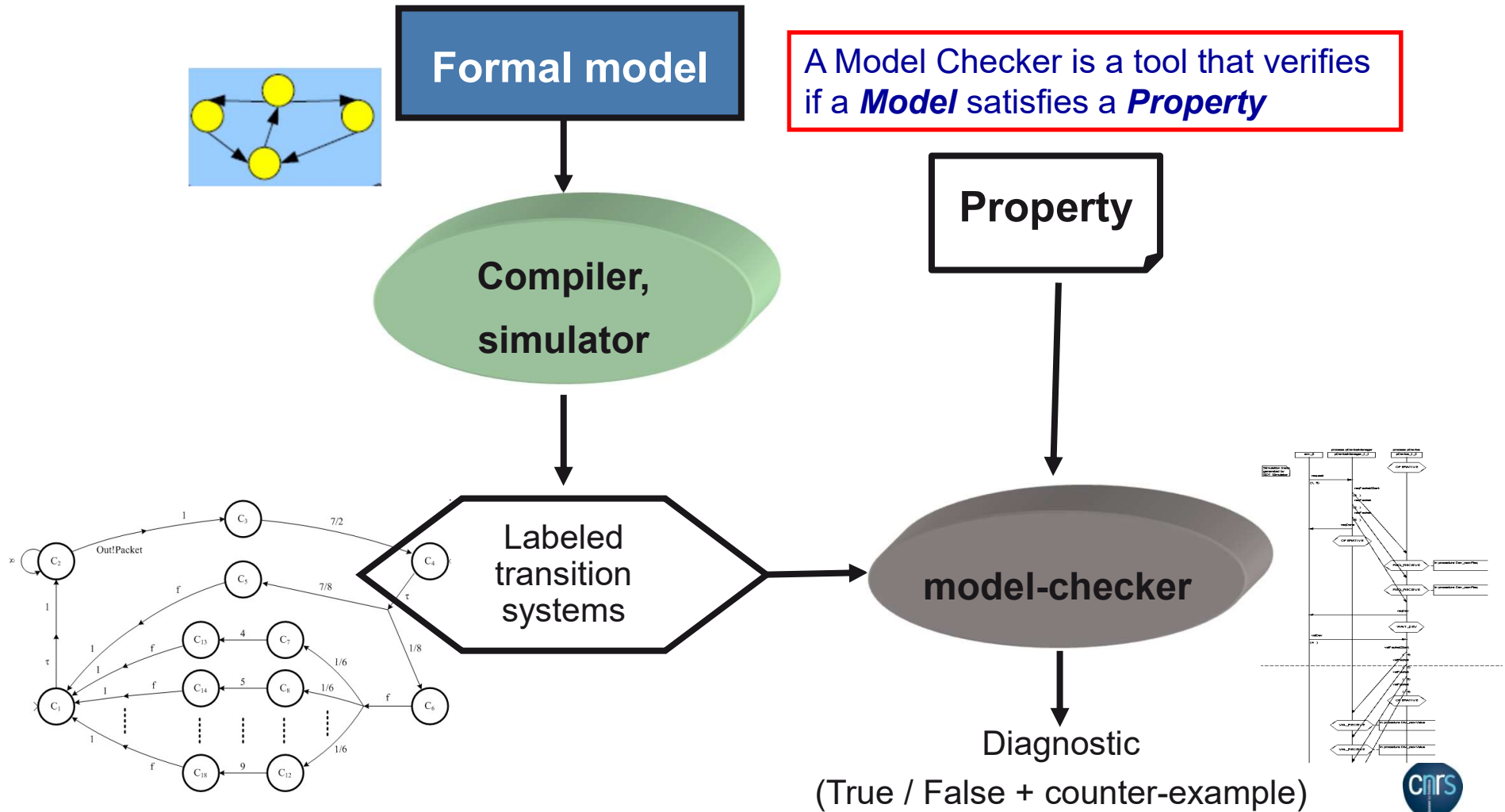
• Code verification

- ❑ Static analysis – no formal models
- ❑ Reverse engineering
- ❑ BLAST, SLAM for C prog.
- ❑ Bandera: JAVA
- ❑ Verisoft: C++

• 3 kinds of methods

- ❑ Model equivalences
- ❑ Deductive methods (proof)
- ❑ Model checking

Model-checking Basis



Model: a term with so many meanings !

- Here models – as they are used for model-checking are just *annotated graphs*:

- A finite set of states, S
- Some initial state s_0
- A transition relation between states, $T \subseteq S \times S$
- A finite set of atomic propositions, AP
- A labelling function $L : S \rightarrow P(AP)$

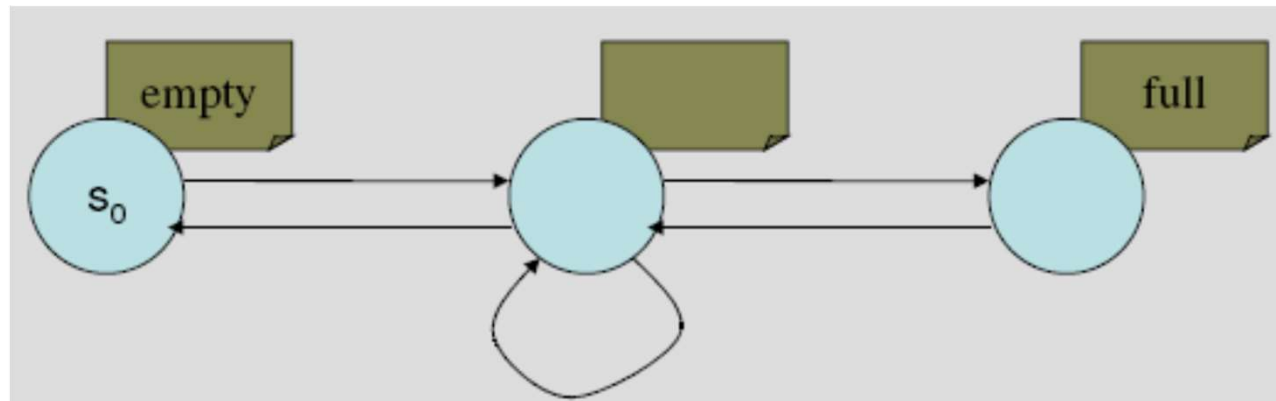
- known as a Kripke structure:

- Labelled Transition systems, LTS
- Finite State machines, FSM
- State charts, ...



** For a physicist a “model” is a differential equation;
For a biologist, it may be ... mice or frogs*

An Example



$AP = \{\text{empty}, \text{full}\}$

Some LTL formula that are valid for this model:

$\text{empty} \Rightarrow (X \neg \text{empty})$

$\text{full} \Rightarrow (X \neg \text{full})$

(X is for neXt)

Systems are the actual objects of interest

■ How to ensure that a system satisfies certain properties?

- But what are *properties* ?!

■ Properties?

1. Texts in natural languages...

“**Calls to lock and unlock must** alternate.”

2. Formulas in a given specification logic

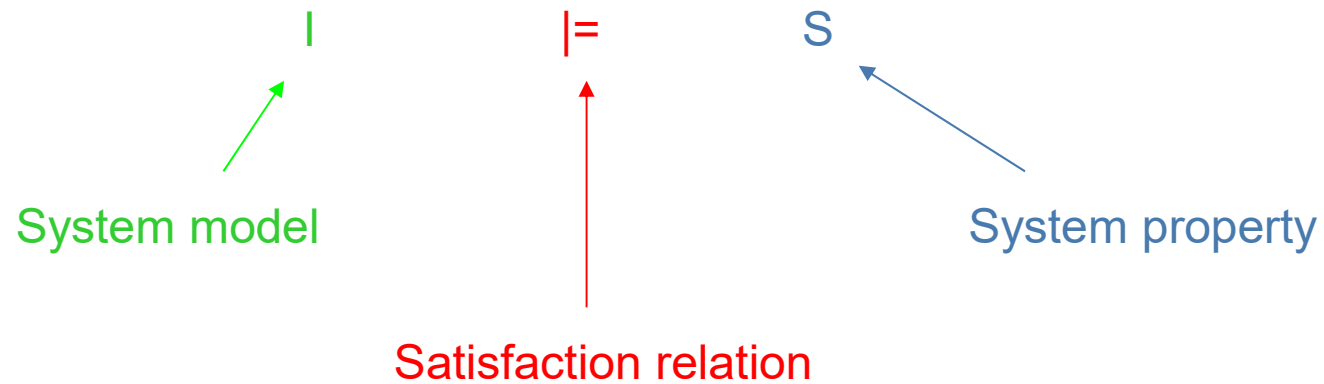
$(\text{locked} \Rightarrow \text{X unlocked}) \wedge (\text{unlocked} \Rightarrow \text{X locked})$

3. Sets of mandatory or forbidden behaviors

Kinds of functional properties

Reachability	A state in a system may be reached
	<i>The train may cross the railroad crossing</i>
Liveness	Under some conditions, an event will come
	<i>When the train announced its arrival, the gate is closed</i>
Safety	A non desired event will never occur
	<i>It is not possible to have the gate open while the train cross the railroad crossing.</i>
No deadlock	The system will never reach a state from which it can not evolve anymore.
	<i>When the gate is closed, it can still be opened.</i>
Fairness	An event will occur indefinitely often
	<i>The gate will be open indefinitely often.</i>

Model-checking problem

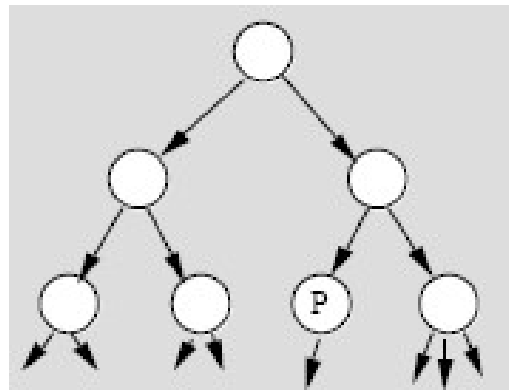


The CTL Logic

Computation Tree Logic

- CTL allows to reason on computation tree

Examples



There exists a path with a state in which P holds

EF P

Temporal operators on an execution : X, F, G, U

- **X φ** : the next state satisfies φ (neXt)
- **F φ** : there exists a state in the future which satisfies φ (Future)

- **G φ** : all the states satisfy φ (Global)

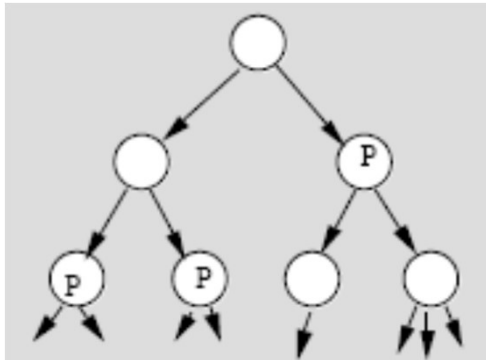
$$G \varphi (= \neg F \neg \varphi)$$

- **$\varphi U \psi$** : a state in which ψ holds and up to this state φ holds true (Until)

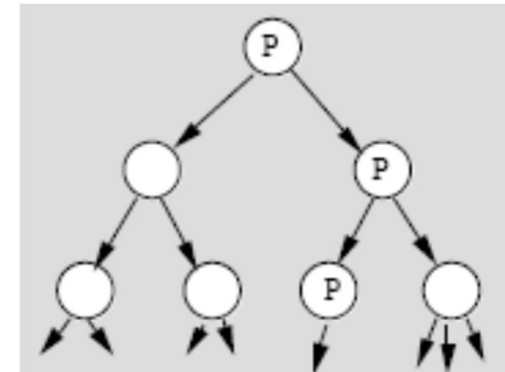
$$F \psi \Leftrightarrow \text{true} U \psi$$



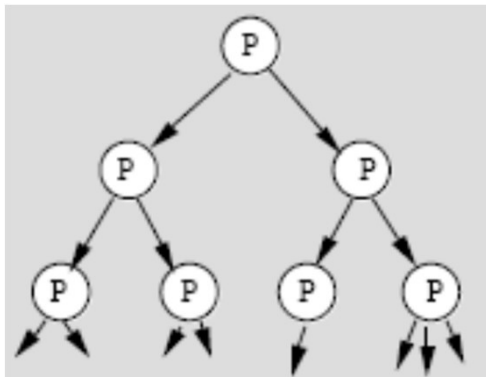
EXAMPLES



On each path there exists a state in which P holds true
 $AF P (= \neg E \neg F P)$



There exists an infinite path on which P holds in each state
 $EG P (= E \neg F \neg P)$



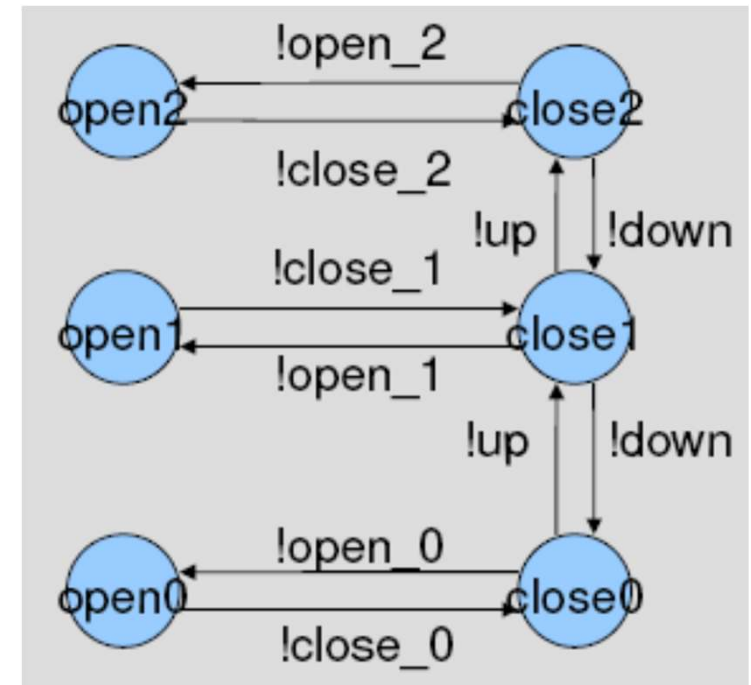
In all reachable states, P holds true
 $AG P (= \neg EF \neg P)$

The temporal operators are of two types
 - on an execution (a path) – E
 - on all executions (all paths) – A

Models - Reminder

■ A model is:

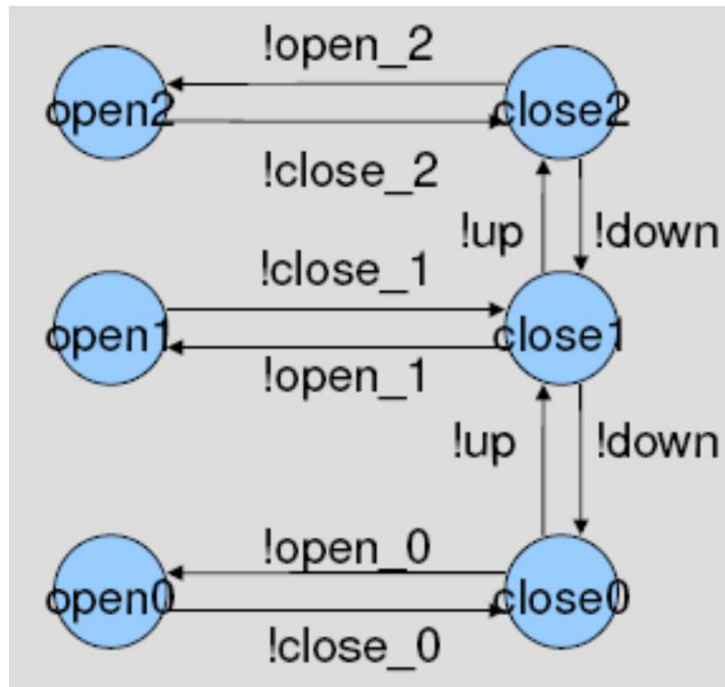
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Formulas associated to the states of the automaton

$L(\text{open}_i) = \{\text{open, level} = i\}, i=0,1,2$

$L(\text{close}_i) = \{\neg \text{open, level} = i\} i=0,1,2$

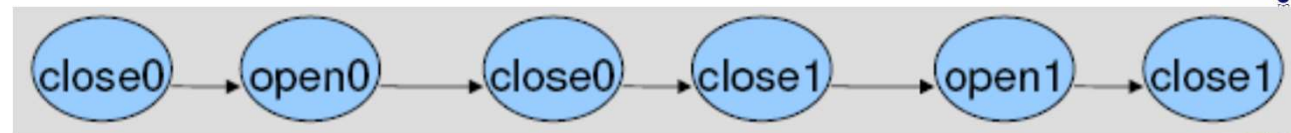


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an execution of the automaton

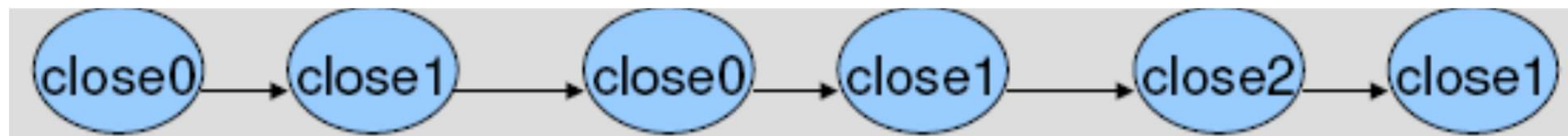


$s,0 \models X \text{ open} \quad s,0 \models F \neg \text{close}$

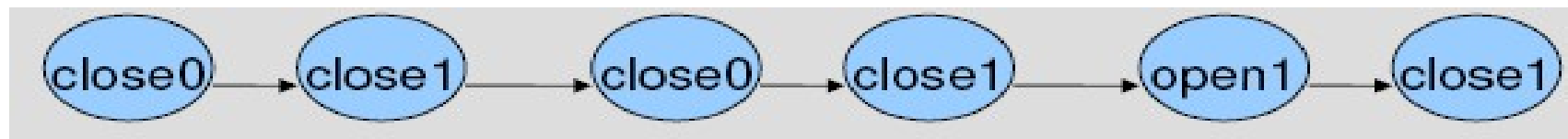
$s,2 \models X \neg \text{open} \wedge X \text{ level} = 1$

$s,i \models G F \neg \text{open} \quad i = 0, \dots, 5$

Notation: $s \models P \Leftrightarrow s,0 \models P$



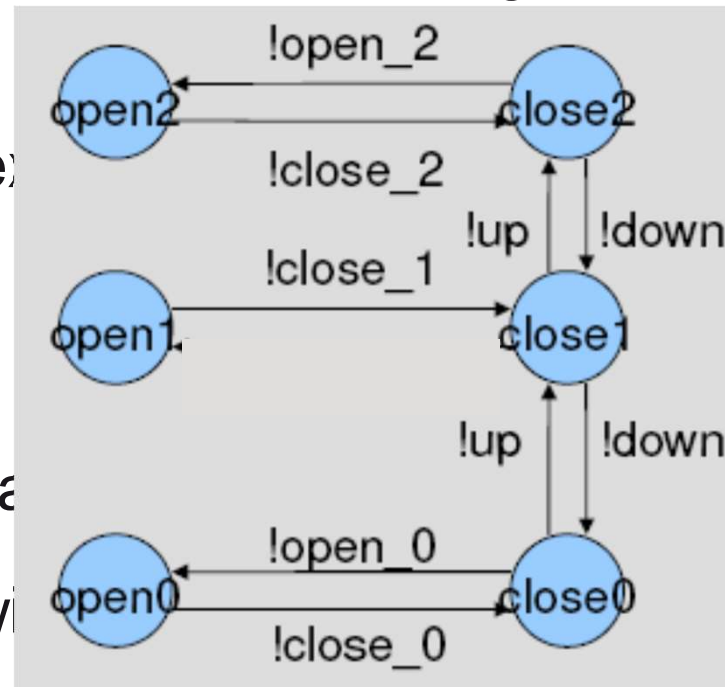
$s \models G \neg \text{open}$



$s \models \neg \text{open} \cup \text{level} = 1$

Temporal operators on all executions : A, E

- $A \varphi$: all the executions starting from the current state satisfy φ
- $E \varphi$: there exists an execution starting from the current state φ



- $E F \varphi$: we can reach a state where φ is true

- $A F \varphi$: we will reach a state where φ is true

safety property

liveness property

$s,3 \models A X \neg \text{open}$

Examples

Asc the controller of the lift :

$$\text{Asc} \models E G \neg \text{open}$$

$$\text{Asc} \models AG (\text{open} \Rightarrow AX \neg \text{open})$$

$$\text{Asc} \models AG (\neg \text{open} \Rightarrow EX \text{open})$$

Precise definition of CTL

■ Syntactical restrictions:

- Each temporal operator X, F, G, U have to be on immediate scope of a A or E , the combinations are:

- **AX, AF, AG, AU, EX, EF, EG, EU**

■ Syntax: atomic propositions are CTL formulas

- if f and g are CTL formulas, then

$\neg f$, $f \wedge g$, **AX f**, **EX f**, **A(fUg)**, **E(fUg)** are **also** CTL formulas

■ Extensions :

- $f \vee g = \neg(\neg f \wedge \neg g)$
- $AF\ g = A(\text{true} \ U\ g)$ $EF\ g = E(\text{true} \ U\ g)$
- $AG\ f = \neg E(\text{true} \ U\ \neg f)$ $EG\ f = \neg A(\text{true} \ U\ \neg f)$

Semantic of CTL

- $s \models f$ (f atomic) iff $f \in L(s)$
- $s \models \neg f$ iff $s \not\models f$
- $s \models f \wedge g$ iff $s \models f$ and $s \models g$
- $s, 0 \models AX f$ iff for all s such that $s_0 = s, 0$, $s, 1 \models f$
- $s, 0 \models EX f$ iff it exists a s such that $s_0 = s, 0$ and $s, 1 \models f$
- $s, 0 \models A(f U g)$ iff for all s s.t. $s_0 = s, 0$, it exists $i \geq 0$ s.t. $s, i \models g$ and
for all $j < i$, $s, j \models f$
- $s, 0 \models E(f U g)$ iff
it exists a s s.t. $s_0 = s, 0$ and
it exists $i \geq 0$ s.t. $s, i \models g$ and
for all $j < i$, $s, j \models f$

Cons and pro of CTL

- 😊 Model checking of linear complexity
- 😞 difficulties or unwillingness to express some kinds of properties (but they are advanced techniques resolving that issue!)

Other temporal logics:

CTL*, PLTL (PSPACE complet), FCTL (*Fairness*), TCTL (*Timers*), Logics with *past*: no model-checkers.

Exercises

■ See the PDF